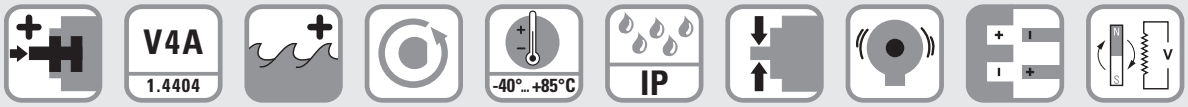
Compact, robust electronic multiturn, magnetic | **Sendix M3663R (shaft)** | **SSI**

The Sendix M36 with Energy Harvesting Technology is an electronic multiturn encoder in miniature format, without gear and without battery.

The "R"obust version is particularly suitable for use in harsh environments. Protected up to IP69k, resistance against shock and extreme temperature fluctuations, the Sendix M36 encoder is suitable even for demanding outdoor applications.

e1 pending · cULus · Ex 2/22 pending · RoHS · SSI



Safety-Lockplus™ · Standard option stainless steel · Standard option seawater resistant · High rotational speed · Temperature range · High protection level · High shaft load capacity · Shock / vibration resistant · Reverse polarity protection · Energy Harvesting

Highest robustness

- Sturdy bearing construction in Safety-Lockplus™ design for particularly high resistance.
- Extra large bearings.
- Mechanically protected shaft seal.
- Protection level IP66, IP67 and IP69k in one device.
- Wide temperature range -40°C ... +85°C.
- Without gear and without battery, thanks to the Energy Harvesting technology.

Application oriented

- Absolute accuracy ±1°.
- Repeat accuracy ±0.2°.
- Short control cycles, clock frequency with SSI up to 2 MHz.
- Max. resolution 38 bit (14 bit ST + 24 bit MT).

Order code Shaft version

8.M3663R.[a][b][c][d].[e][f][g]2 (Type)

If for each parameter of an encoder the **underlined preferred option** is selected, then the delivery time will be 10 working days for a maximum of 10 pieces. Qts. up to 50 pcs. of these types generally have a delivery time of 15 working days. 10 by 10

a *Version*
1 = standard [1]
clamping flange ø 42 mm [1.65"]
7 = stainless steel V4A [2]
clamping flange ø 42 mm [1.65"]
all metal parts accessible from outside are out of stainless steel V4A

b *Shaft (ø x L), with flat*
1 = ø 6 x 12.5 mm [0.24 x 0.49"]
3 = ø 8 x 15 mm [0.32 x 0.59"]
5 = ø 10 x 20 mm [0.39 x 0.79"]
2 = ø 1/4" x 12.5 mm [0.49"]
E = ø 10 x 20 mm [0.39 x 0.79"], stainless steel V4A

c *Interface / power supply*
2 = SSI / 10 ... 30 V DC

d *Type of connection*
2 = radial cable, 1 m [3.28'] PUR
B = radial cable, special length PUR *)
4 = radial M12 connector, 8-pin
*) Available special lengths (connection type B):
2, 3, 5, 8, 10, 15 m [5.56, 9.84, 16.40, 26.25, 32.80, 49.21']
order code expansion .XXXX = length in dm
ex.: 8.M3663R.132B.G322.0030 (for cable length 3 m)

e *Code*
B = SSI, binary
G = SSI, gray

f *Resolution (singleturn)*
A = 10 bit ST
2 = 12 bit ST
3 = 13 bit ST
4 = 14 bit ST

g *Resolution (multiturn)*
2 = 12 bit MT
6 = 16 bit MT
A = 20 bit MT
4 = 24 bit MT

Optional on request
- Ex 2/22 (only for connection type 4)
- other shaft diameters out of V4A stainless steel

1) Not in conjunction with shaft type "E".
2) Only in conjunction with shaft type "E" + type of connection "4" .

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Mounting accessory for shaft encoders		Order no.
Coupling	Bellows coupling ø 19 mm [0.75"] for shaft 8 mm [0.32"]	**8.0000.1102.0808** 1)

Connection technology		Order no.
Cordset, pre-assembled	M12 female connector with coupling nut, 8-pin 2 m [6.56'] PUR cable	**05.00.6051.8211.002M** 1)
Connector, self-assembly (straight)	M12 female connector with coupling nut, 8-pin	**05.CMB 8181-0** 1)

Further accessories can be found in the accessories section or in the accessories area of our website at: www.kuebler.com/accessories.
Additional connectors can be found in the connection technology section or in the connection technology area of our website at: www.kuebler.com/connection_technology.

Technical data

Mechanical characteristics

Maximum speed		4000 min^{-1} 2000 min^{-1} (continuous)	
Starting torque at 20°C [68°F]		< 0.01 Nm	
Shaft load capacity	radial	80 N	
	axial	40 N	
Weight		approx. 0.2 kg [7.06 oz]	
Protection acc. to EN 60529/DIN 40050-9		IP66, IP67, IP69k	
Working temperature range		-40°C ... +85°C [-40°F ... +185°F]	
Materials		**version "1"** (standard)	**version "7"** (stainless steel)
	shaft	V2A	V4A
	flange	aluminum	V4A
	housing	zinc die-cast	V4A
	cable	PUR	–
Shock resistance acc. to EN 60068-2-27		5000 m/s^2, 4 ms	
Vibration resistance acc. to EN 60068-2-6		300 m/s^2, 10 ... 2000 Hz	

Electrical characteristics

Power supply	10 ... 30 V DC
Current consumption (no load)	max. 30 mA
Reverse polarity protection of the power supply	yes
Short-circuit proof outputs	yes 2)
e1 compliant acc. to (pending)	EU guideline 2009/19/EC (acc. to EN 55025, ISO 11452 and ISO 7637)
UL approval	File 224618
CE compliant acc. to	EMC guideline 2014/30/EU RoHS guideline 2011/65/EU

SSI interface

Output driver		RS485 transceiver type
Permissible load / channel		max. +/- 30 mA
Signal level	HIGH	typ 3.8 V
	LOW with I_{Load} = 20 mA	typ 1.3 V
Resolution singleturn		10 ... 14 bit
Absolute accuracy 3)		±1°
Repeat accuracy		±0.2°
Number of revolutions (multiturn)		max. 24 bit
Code		binary or gray
SSI clock rate		50 kHz ... 2 MHz
Data refresh rate		2 ms
Monoflop time		≤ 15 µs

Note: If the clock cycle starts within the monoflop time a second data transfer begins with the same data. If the clock cycle starts after the monoflop time the cycle begins with the new values. The update rate is dependent on the clock speed, data length and monoflop time.

SET input

Input		active HIGH
Input type		comparator
Signal level (+V = power supply)	HIGH	min. 60 % of +V, max: +V
	LOW	max. 30 % of +V
Input current		< 0.5 mA
Min. pulse duration (SET)		10 ms
Input delay		1 ms
New position data readable after		1 ms
Internal processing time		200 ms

The encoder can be set to zero at any position by means of a HIGH signal on the SET input. Other preset values can be factory-programmed. The SET input has a signal processing time of approx. 1 ms, after which the new position data can be read via SSI or BiSS. Once the SET function has been triggered, the encoder requires an internal processing time of typ. 200 ms; during this time the power supply must not be switched off.
The SET function should be carried out whilst the encoder is at rest.

If this input is not used, it should be connected to 0 V (Encoder ground GND) in order to avoid interferences.

1) Not for version "7" (V4A stainless steel)
2) Short circuit proof to 0 V or to output when power supply correctly applied.
3) Over the whole temperature range.

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DIR input

Direction input: A HIGH signal switches the direction of rotation from the default cw to ccw. This inverted function can also be factory-programmed.

If this input is not used, it should be connected to 0 V (Encoder ground GND) in order to avoid interferences.

Response time (DIR input) 1 ms

Power-ON

After Power-ON the device requires a time of approx. 150 ms before valid data can be read.

Hot plugging of the encoder should be avoided.

Terminal assignment

Interface	Type of connection	Features	Cable (isolate unused wires individually before initial start-up)								
2	2, B	SET, DIR	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	⏚
			Cable color:	WH	BN	GN	YE	GY	PK	BU	RD	shield

Interface	Type of connection	Features	M12 connector, 8-pin								
2	4	SET, DIR	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	⏚
			Pin:	1	2	3	4	5	6	7	8	PH

+V: Encoder power supply +V DC
0 V: Encoder power supply ground GND (0 V)
C+, C-: Clock signal
D+, D-: Data signal
SET: Set input
DIR: Direction input
PH ⏚: Plug connector housing (shield)

Top view of mating side, male contact base

M12 connector, 8-pin

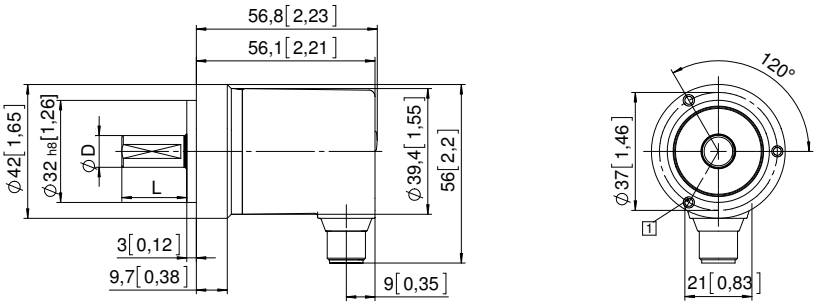
Dimensions

Dimensions in mm [inch]

Aluminum, clamping flange, ø 42 [1.65] version 1

1 3 x M3, 6 [0.24] deep

D	Fit	L
6 [0.24]	h7	12.5 [0.49]
8 [0.32]	h7	15 [0.59]
10 [0.39]	f7	20 [0.79]
1/4“	h7	12.5 [0.49]



Stainless steel V4A clamping flange, ø 42 [1.65] version 7

1 4 x M4, 8 [0.31] deep

D	Fit	L
6 [0.24]	h7	12.5 [0.49]
8 [0.32]	h7	15 [0.59]
10 [0.39]	f7	20 [0.79]
1/4“	h7	12.5 [0.49]