

# Multi-axis controller

## V25



The multi-axis controller V25 is available in either single-axis or multi-axis options and is a robust controller used commonly in electro-hydraulic applications. With many output options including voltage, amperage and switching contacts and many handle options the V25 series is highly customisable. The V25 is resistant to oil, maritime conditions e.g. offshore / vessels, UV radiation typically from the sun.

### Technical data

Mechanical life V25	8 million operating cycles
Supply voltage	See interface
Operation temperature	-40°C to +60°C
Storage temperature	-50°C to +80°C
Degree of protection	IP54 (optional IP67)
Functional safety	PLd (EN ISO 13849) possible



1

	V25	S8	P	T	Example	- Z	- B	- E...	- S...	- X
<b>Basic unit</b>										
V25.1 1-axis										
V25 2-axis										
<b>Control-handle long</b>										
Standard 100mm										
S8 +20mm										
*Only available in combination with grip!										
<b>Gate</b>										
P Cross gate										
<b>Grip / palm grip</b>										
Knob (included in basic unit!)										
M Mechanical zero interlock										
T Knob with dead man										
H Knob with signal button										
D Knob with push button KDA/70										
B ... Palm grip B... (see page palm grip 147)										
<b>Spring return (includet in basic unit!)</b>										
Z Spring return										
<b>Cover housing (description see page 187)</b>										
B Cover housing										
<b>Interface (description see on the following page)</b>										
E0xx Switching output										
E1xx Voltage output										
E2xx Current output										
E3xx CAN-interface										
E4xx CANOpen Safety interface										
<b>Plug connectors</b>										
S.. Standard plug connectors (see page 129)										
<b>Special model</b>										
X Special / customer specified										

Technical details may vary based on configuration or application! Technical data subject to change without notice!

# Multi-axis controller

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### Combination possibilities with our handles



### Digital output

Supply voltage	9-32V DC	
Current carrying capacity	Direction signal 150mA Zero position signal 500mA	
Mounting depth A	60mm	
Wiring	1. cable 14x0,25mm <sup>2</sup> 500mm long without plug connector 2. cable 14x0,25mm <sup>2</sup> (for axis 3-4 or grip function) 500mm long without plug connector <i>Optional with plug connector (standard plug connectors see page 129)</i>	S
2 Direction signals + 1 zero position signal (galvanically isolated) per axis	1 axis 2 axis	E001 1 2

### Voltage output (not stabilized)

Supply voltage	4,75-5,25V DC	
Current carrying capacity	Direction signal 8mA	
Mounting depth A	60mm	
Wiring	1. cable 14x0,25mm <sup>2</sup> 500mm long without plug connector 2. cable 14x0,25mm <sup>2</sup> (for axis 3-4 or grip function) 500mm long without plug connector <i>Optional with plug connector (standard plug connectors see page 129)</i>	S
0,5...2,5...4,5V redundant + 2 direction signals per axis	1 axis 2 axis	E104 1 2
	<b>Output options</b>	
	Characteristic:	
	Inverse dual	1
	Dual	2
	Inverse Dual with dead zone +/- 3°	3
	Dual with dead zone +/- 3°	4

# Multi-axis controller

## V25



### Voltage output

Supply voltage	9-32V DC (*11,5-32)
Current carrying capacity	Direction signal 150mA
	Zero position signal 500mA
Mounting depth A	60mm
Wiring	1. cable 14x0,25mm <sup>2</sup> 500mm long without plug connector 2. cable 14x0,25mm <sup>2</sup> (for axis 3-4 or grip function) 500mm long without plug connector <small>Optional with plug connector (standard plug connectors see page 129)</small>

0,5...2,5...4,5V redundant + 2 direction signals + 1 zero position signal (galvanically isolated) per axis

1 axis	E112 1
2 axis	2
3 axis*	3
4 axis*	4

0...5...10V redundant + 2 direction signals + 1 zero position signal (galvanically isolated) per axis, supply voltage 11,5 - 32V DC

1 axis	E132 1
2 axis	2
3 axis*	3
4 axis*	4

10...0...10V + 2 direction signals + 1 zero position signal (galvanically isolated) per axis, supply voltage 11,5 - 32V DC,  
sensor redundant with error monitoring and error signal

1 axis	E136 1
2 axis	2
3 axis*	3
4 axis*	4

### Output options

Characteristic:

Inverse dual *1	1
Dual *1	2
Inverse dual with dead zone +/- 3° *1	3
Dual with dead zone +/- 3° *1	4

\*1 not combinable with output E136X

Single *2	5
Single with dead zone *2	6

\*2 not combinable with output E112X and E132X

Digital output signals:

Output signals standard:	0
Direction signals and zero position signals 1,5A 24VDC	1

\*Axis for handle functions, interface can vary depending upon actuation element!

Voltage output with other value on request!

### Current output

Supply voltage	9-32V DC
Current carrying capacity	Direction signal 150mA
	Zero position signal 500mA
Mounting depth A	60mm
Wiring	1. cable 14x0,25mm <sup>2</sup> 500mm long without plug connector 2. cable 14x0,25mm <sup>2</sup> (for axis 3-4 or grip function) 500mm long without plug connector <small>Optional with plug connector (standard plug connectors see page 129)</small>

0...10...20mA + 2 direction signals + 1 zero position signal (galvanically isolated) per axis, sensor redundant with error monitoring and error signal

1 axis	E206 1
2 axis	2
3 axis*	3
4 axis*	4

20...0...20mA + 2 direction signals + 1 zero position signal (galvanically isolated) per axis, sensor redundant with error monitoring and error signal

1 axis	E208 1
2 axis	2
3 axis*	3
4 axis*	4

4...12...20mA + 2 direction signals + 1 zero position signal (galvanically isolated) per axis, sensor redundant with error monitoring and error signal

1 axis	E214 1
2 axis	2
3 axis*	3
4 axis*	4

20...4...20mA + 2 direction signals + 1 zero position signal (galvanically isolated) per axis, sensor redundant with error monitoring and error signal

1 axis	E216 1
2 axis	2
3 axis*	3
4 axis*	4

### Output options

Single	5
Single with dead zone +/- 3°	6

Digital output signals:

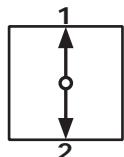
Output signals standard:	0
Direction signals and zero position signals 1,5A 24VDC	1

\*Axis for handle functions, interface can vary depending upon actuation element!

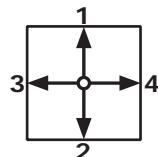
Current output with other value on request!

**Identification of the installation variants with switching directions:**

V25.1



V25



**CAN**

Supply voltage	9-32V DC
Idle current consumption	120mA (24VDC)
Current carrying capacity	Direction signal 100mA Zero position signal 100mA External digital output for LEDs 5mA - 30mA (dependent on the number of LEDs) Digital switching output (potential-free) 100mA
Mounting depth A	60mm (Expansion stage 1) 75mm (Expansion stage 2) 95mm (Expansion stage 3)
Protocol	CANOpen CiA DS 301 or SAE J1939
Baud rate	20kBit/s to 1Mbit/s (standard 250kBit/s)
Output value	255...0...255
Wiring	CAN (IN) cable 300mm with plug connector M12 (male) CAN (OUT) cable 300mm with plug connector M12 (female) External in-/outputs cable 300mm long without plug connector External in-/outputs cable 300mm long without plug connector (additional from 32 in-/outputs) <i>Optional with plug connector (standard plug connectors see page 129)</i>

**CAN V25 expansion stage 1**

E304 1

- 4 analog joystick axis
- 15 digital joystick functions
- Input for capacitive sensor

Main-axis with additional digital outputs separately wired (not via CAN)

- 2 direction signals per main axis

1

**CAN V25 expansion stage 2**

E305 1

- 7 analog joystick axis
- 15 digital joystick functions
- 2 inputs for capacitive sensors

With additional external in-/outputs

- 8 external LED-outputs (dimmable), 1 switching output (potential-free, 100mA), 8 external digital inputs
- 16 external LED-outputs (dimmable), 1 switching output (potential-free, 100mA), 16 external digital inputs

2

3

*External LED-outputs can be used in the grip for LEDs*

### CAN V25 expansion stage 3

- 10 analog joystick axis
- 15 digital joystick functions
- 2 inputs for capacitive sensors

E306 1

With additional external in-/outputs

- 8 external LED-outputs (dimmable), 2 switching outputs (potential-free, 100mA), 8 external digital inputs
- 16 external LED-outputs (dimmable), 2 switching outputs (potential-free, 100mA), 16 external digital inputs
- 24 external LED-outputs (dimmable), 2 switching outputs (potential-free, 100mA), 24 external digital inputs
- 32 external LED-outputs (dimmable), 2 switching outputs (potential-free, 100mA), 32 external digital inputs

2  
3  
4  
5

*External LED-outputs can be used in the grip for LEDs*

Main-axis with additional digital outputs separately wired (not via CAN)

- 2 direction signals + 1 zero position signal (potential-free) per axis

3

*With additional analog outputs on request!*

### CANopen safety

Supply voltage	9-32V DC
Idle current consumption	120mA (24V DC)
Current carrying capacity	Direction signal 100mA Zero position signal 100mA (potential-free) External digital output for LEDs 5mA - 30mA (dependent on the number of LEDs) Digital switching output (potential-free) 100mA
Baud rate	20kBit/s to 1MBit/s (standard 250kBit/s)
Output value	255...0...255
Mounting depth	60mm (Expansion stage 1) 75mm (Expansion stage 2) 95mm (Expansion stage 3)
Protocol	CANopen Safety CIA 304
Wiring	CAN (IN) cable 300mm with plug connector M12 (male) CAN (OUT) cable 300mm with plug connector M12 (female) External in-/outputs cable 300mm long without plug connector External in-/outputs cable 300mm long without plug connector (additional from 32 in-/outputs) Optional with plug connector ( <i>standard plug connectors see page 129</i> )

S

### CANopen Safety expansion stage 1

- 4 analog joystick axis
- 15 digital joystick functions
- Input for capacitive sensor

E404 1

Main-axis with additional digital outputs separately wired (not via CAN)

- 2 direction signals per main axis

1

### CANopen safety expansion stage 2

- 7 analog joystick axis
- 15 digital joystick functions
- 2 inputs for capacitive sensors

E405 1

With additional external in-/outputs

- 8 external LED-outputs (dimmable), 1 switching output (potential-free, 100mA), 8 external digital inputs
- 16 external LED-outputs (dimmable), 1 switching output (potential-free, 100mA), 16 external digital inputs

2  
3

*External LED-outputs can be used in the grip for LEDs*

Technical details may vary based on configuration or application! Technical data subject to change without notice!

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### CANopen safety expansion stage 3

- 10 analog joystick axis
- 15 digital joystick functions
- 2 inputs for capacitive sensor

E406 1

With additional external in-/outputs

- 8 external LED-outputs (dimmable), 2 switching outputs (potential-free, 100mA), 8 external digital inputs
- 16 external LED-outputs (dimmable), 2 switching outputs (potential-free, 100mA), 16 external digital inputs
- 24 external LED-outputs (dimmable), 2 switching outputs (potential-free, 100mA), 24 external digital inputs
- 32 external LED-outputs (dimmable), 2 switching outputs (potential-free, 100mA), 32 external digital inputs

2

3

4

5

*External LED-outputs can be used in the grip for LEDs*

Main-axis with additional digital outputs separately wired (not via CAN)

- 2 direction signals + 1 zero position signal (potential-free) per axis

3

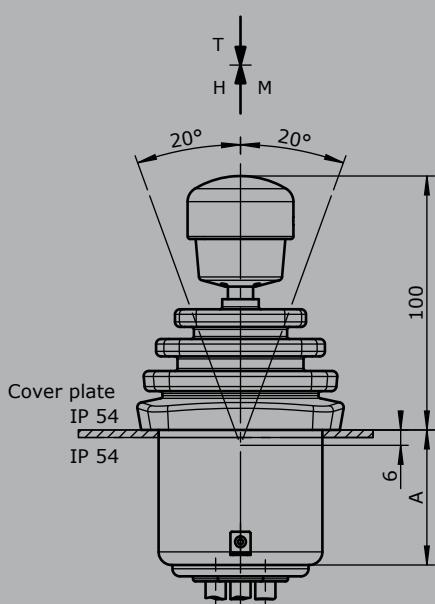
*With additional analog outputs on request!*

1

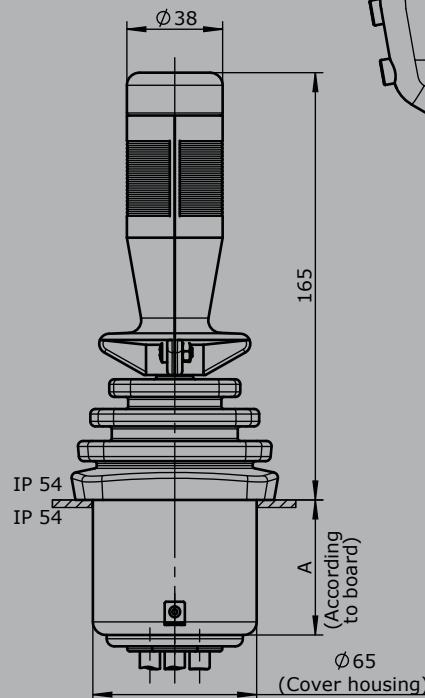
### Attachments

Z01 Mating connector M12 male insert with 2m cable	20201140
Z02 Mating connector M12 female insert with 2m cable	20202298

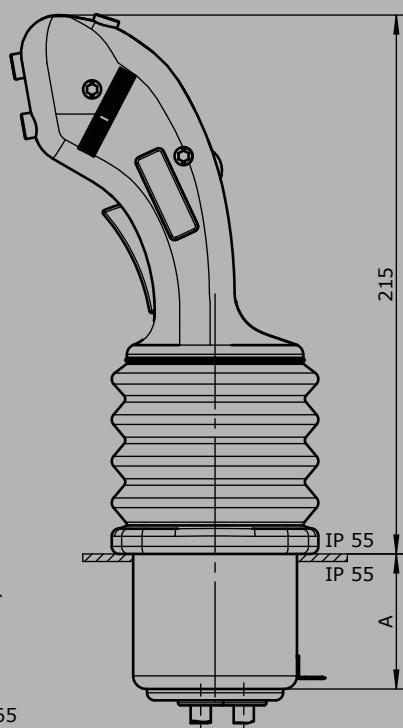
T = Dead man's button  
H = Signal button  
M = Latch for mechanical zero interlock



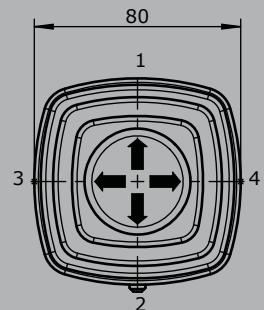
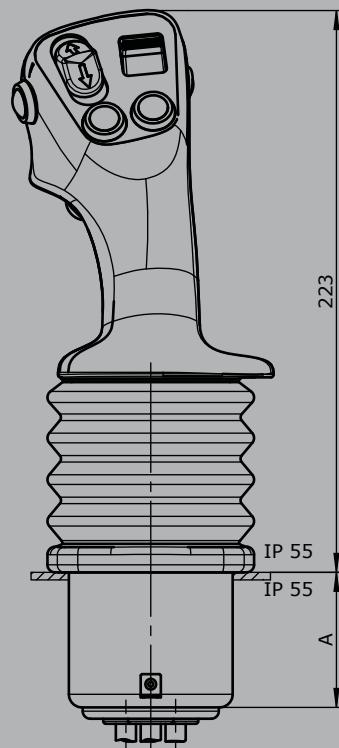
Palm grip B1



Palm grip B3



Palm grip B25



Hole pattern

