



# Absolute encoders – multiturn

<b>Standard</b> <b>Motor-Line, electronic multiturn, optical</b>	<b>Sendix F5888M (hollow shaft)</b>	<b>CANopen</b>
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Mounting accessory for hollow shaft encoders	Dimensions in mm [inch]	Order no.
<b>Cylindrical pin, long</b> for flange with spring element (flange type 1)	with fixing thread 	<b>8.0010.4700.0000</b>

Further accessories can be found in the accessories section or in the accessories area of our website at: [www.kuebler.com/accessories](http://www.kuebler.com/accessories).  
 Suitable connectors can be found in the connection technology section or in the connection technology area of our website at: [www.kuebler.com/connection\\_technology](http://www.kuebler.com/connection_technology).

## Technical data

Mechanical characteristics	
<b>Maximum speed</b>	9000 min <sup>-1</sup> , 6000 min <sup>-1</sup> (continuous)
<b>Starting torque at 20°C [68°F]</b>	< 0.01 Nm
<b>Mass moment of inertia</b>	6.0 x 10 <sup>-6</sup> kgm <sup>2</sup>
<b>Load capacity of shaft</b>	radial 80 N axial 40 N
<b>Weight</b>	approx. 0.45 kg [15.87 oz]
<b>Protection</b>	IP65
<b>Working temperature range</b>	-40°C ... +85°C [-40°F ... +185°F] <sup>1)</sup>
<b>Material</b>	hollow shaft stainless steel flange aluminum housing zinc die-cast cable PVC
<b>Shock resistance acc. to EN 60068-2-27</b>	2500 m/s <sup>2</sup> , 6 ms
<b>Vibration resistance acc. to EN 60068-2-6</b>	100 m/s <sup>2</sup> , 55 ... 2000 Hz

Electrical characteristics	
<b>Power supply</b>	10 ... 30 V DC
<b>Power consumption (no load)</b>	max. 80 mA
<b>Reverse polarity protection of the power supply</b>	yes
<b>UL approval</b>	file 224618
<b>CE compliant acc. to</b>	EMC guideline 2014/30/EU RoHS guideline 2011/65/EU

Diagnostic LED (two-color, red/green)		
<b>LED ON or blinking</b>	red	error display
	green	status display
	combination red / green	error code

Interface characteristics CANopen	
<b>Resolution singleturn</b>	1 ... 65536 (16 bit), scalable default: 8192 (13 bit)
<b>Number of revolutions (multiturn)</b>	max. 65536 (16 bit) scalable only via the total resolution
<b>Total resolution</b>	1 ... 4.294.967.296 (32 bit) default: 25 bit
<b>Code</b>	binary
<b>Interface</b>	CAN high-speed acc. to ISO 11898, Basic- and Full-CAN, CAN specification 2.0 B
<b>Protocol</b>	CANopen profile DS406 V3.2 with manufacturer-specific add-ons, LSS-service DS305 V2.0
<b>Baud rate</b>	10 ... 1000 kbit/s software configurable
<b>Node address</b>	1 ... 127 software configurable
<b>Termination switchable</b>	software configurable
<b>LSS protocol</b>	CIA LSS protocol DS305, global command support for node address and baud rate, selective commands via attributes of the identity object

Incremental track characteristics	
<b>Output driver</b>	RS422 (TTL-compatible)
<b>Permissible load / channel</b>	max. +/- 20 mA
<b>Signal level</b>	HIGH typ. 3.8 V LOW typ. 1.3 V
<b>Short circuit proof outputs</b>	yes <sup>2)</sup>
<b>Resolution</b>	2048 ppr

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1) Temperature measured on the flange – max. 80°C allowable on the cable (fixed installation).  
 2) Short circuit to 0 V or to output, only one channel at a time, power supply correctly applied.

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## General information about CANopen

The CANopen encoders support the latest CANopen communication profile according to DS301 V4.2. In addition, device specific profiles such as encoder profile DS406 V3.2 and DS305 (LSS) are available.

The following operating modes may be selected: Polled Mode, Cyclic Mode, Sync Mode and a High Resolution Sync Protocol. Moreover, scale factors, preset values, limit switch values and many other additional parameters can be programmed via the CAN bus.

When switching the device on, all parameters, which have been saved on an EEPROM to protect them against power failure, are loaded again.

The following output values may be combined in a freely variable way as PDO (PDO mapping): **position, speed, temperature** as well as the **status of the working area**.

The encoders are available with a connector or a cable connection.

The device address and baud rate can be set/modified by means of the software.

The two-color LED located on the back indicates the operating or fault status of the CAN bus, as well as the status of the internal diagnostics.

## Universal scaling function

At the end of the physical resolution of an encoder, **when scaling is active**, an error appears if the division of the physical limit (GP\_U) by the programmed total resolution (TMR) does not produce an integer.

The universal scaling function remedies this problem.

## CANopen Communication Profile DS301 V4.2

Among others, the following functionality is integrated. Class C2 functionality:

- NMT slave.
- Identity object.
- Error behavior object.
- Variable PDO mapping self-start programmable (power on to operational), 4 sending PDO's.
- Node address, baud rate and CANbus / programmable termination.
- Producer / consumer heartbeat.

## CANopen encoder profile DS406 V3.2

The following parameters can be programmed:

- Event mode.
- 2 working areas with 2 upper and lower limits and the corresponding output states.
- Variable PDO mapping for position, speed, work area status, error message, raw data.
- Extended failure management for position sensing.
- User interface with visual display of bus and failure status.
- Customer-specific memory 16 Byte.
- Customer-specific protocol.
- Universal Scaling Function (USF).
- "Watchdog controlled" device.
- Extended diagnostic modes.

## LSS layer setting services DS305 V2.0

- Global support of node-ID and baud rate
- Selective protocol via identity object (1018h)

## Terminal assignment

Interface	Type of connection	Features	Cable (isolate unused wires individually before initial start-up)					
			Signal:	0 V power supply	+V power supply	CAN_L	CAN_H	CAN_GND
2	L, M	Bus IN	Cable color:	WH	BN	YE	GN	GY

Interface	Type of connection	Features	Cable (isolate unused wires individually before initial start-up)									
			Signal:	0 V power supply	+V power supply	CAN_L	CAN_H	CAN_GND	A	$\bar{A}$	B	$\bar{B}$
5	L, M	Bus IN	Cable color:	WH	BN	YE	GN	GY	BK	VT	GY-PK	RD-BU

# Absolute encoders – multiturn

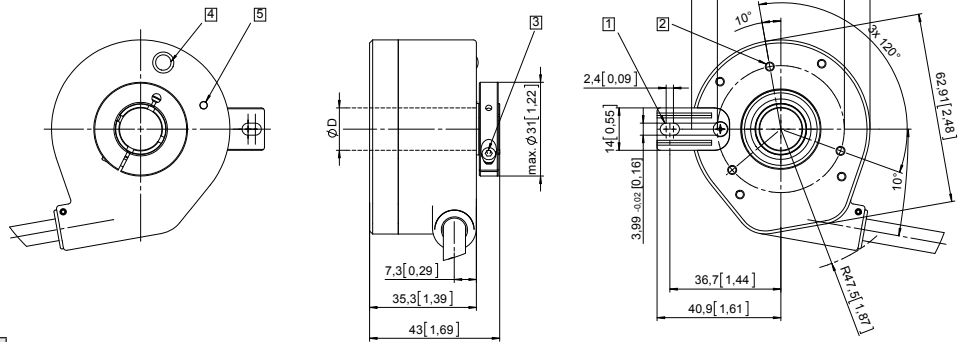
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## Dimensions

Dimensions in mm [inch]

### Flange with spring element, long Flange type 1

- 1 Slot spring element, recommendation: cylindrical pin DIN 7,  $\varnothing$  4 [0.16]
- 2 3 x M3, 6 [0.24] deep
- 3 Recommended torque for the clamping ring 0.6 Nm
- 4 Status-LED
- 5 SET button



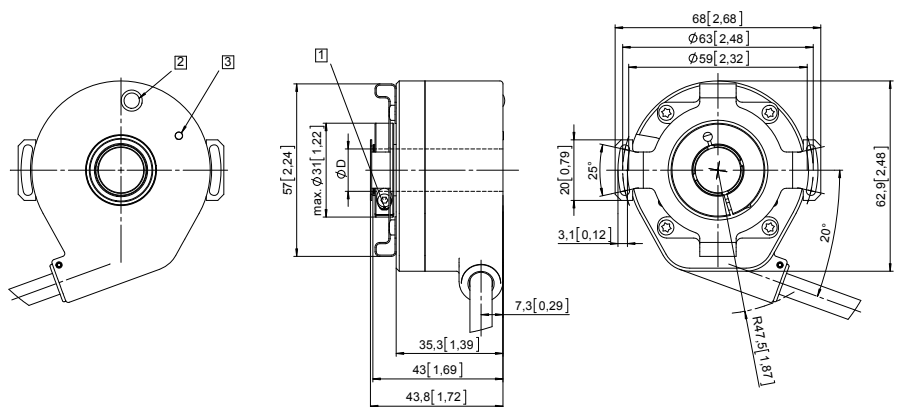
D	Fit
10 [0.39]	H7
12 [0.47]	H7
14 [0.55]	H7
15 [0.59]	H7
1/2 "	H7

### Flange with stator coupling, $\varnothing$ 63 [2.48]

#### Flange type 5

Pitch circle diameter for fixing screws 63 mm [2.48]

- 1 Recommended torque for the clamping ring 0.6 Nm
- 2 Status-LED
- 3 SET button

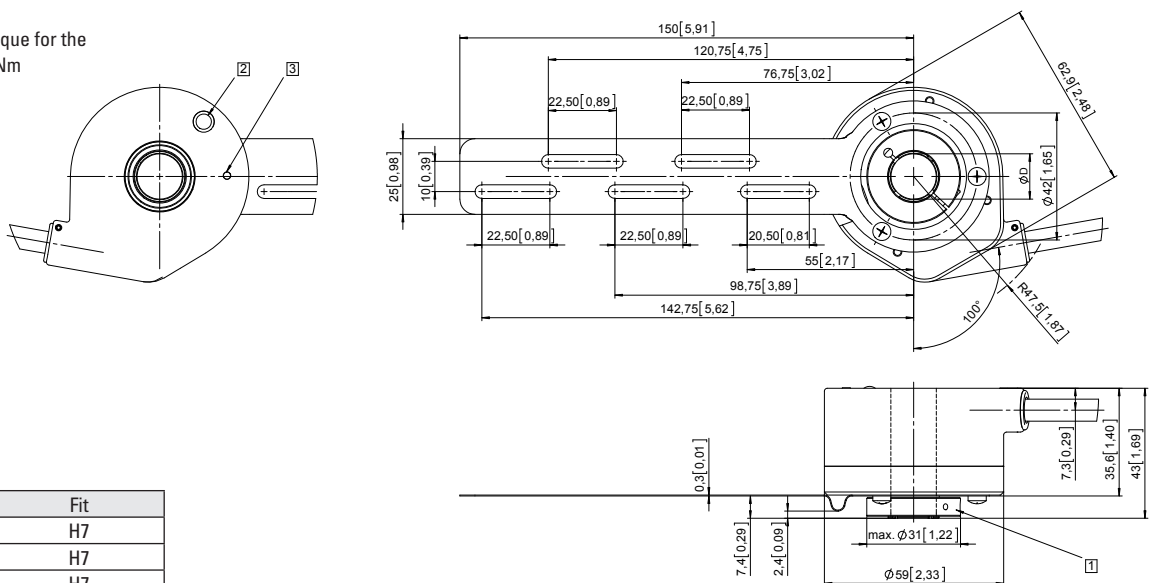


D	Fit
10 [0.39]	H7
12 [0.47]	H7
14 [0.55]	H7
15 [0.59]	H7
1/2 "	H7

### Flange with torque stop, flexible

#### Flange type 9

- 1 Recommended torque for the clamping ring 0.6 Nm
- 2 Status-LED
- 3 SET button



D	Fit
10 [0.39]	H7
12 [0.47]	H7
14 [0.55]	H7
15 [0.59]	H7
1/2 "	H7